

# Uljad Berdica

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## Education

<b>University of Oxford</b> <i>PhD with CDT-Autonomous Intelligent Machines and Systems, Rhodes Scholar 2022</i>	Sep 2022 – Sep 2026 Oxford, UK
<b>New York University (NYU)</b> <i>Bachelor of Science in Electrical Engineering, Magna Cum Laude, University Honors</i>	Aug 2018 – May 2022 USA, UAE, PRC

## Research Work

<b>AI Research Associate for Reinforcement Learning and Optimization</b> <i>Research Scientist in the Optimization Team at JP Morgan AI Research</i>	Jun 2025 - Oct 2025 London, UK
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- **Inspect** datasets of transactions and prices from various statistical perspectives
- **Model** trading problems to design and implement production-ready high-performance solutions
- **Develop** benchmarks and methods for bandit algorithms using natural language context and LLMs as stochastic processes

<b>Unified Offline Reinforcement Learning - JAX Library</b> <i>PhD Researcher at Foerster Lab for AI Research</i>	Aug 2024 – Apr 2025 Oxford, UK
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- **Implemented** SOTA offline RL algorithms in a unified framework in JAX
- **Clean** and consistent algorithmic implementation to track all the relevant tricks required for each method
- **Evaluation** of algorithms using a multi-armed bandit to estimate the online interaction budget required to find the best policy

<b>Diverse Generation for Large Language Models</b> <i>Researcher at Foerster Lab for AI Research and BBC Research and Development</i>	Jul 2024 – June 2025 Oxford, UK
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- **Curated** dataset from published user activity in large social networks and used to fine-tune LLMs
- **Trained** large models using three levels of tensor parallelism on multiple machines
- **Implemented** different clustering algorithms to evaluate the quality and the semantic entropy of the generations

<b>Towards Training Generalist Agents Through an Ensemble of World Models</b> <i>PhD Researcher at Foerster Lab for AI Research</i>	Jan 2023 – Oct 2024 Oxford, UK
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- **Trained** 100s of dynamics models in parallel to use as levels to create a training curriculum
- **Implemented** a recurrent actor-critic network and a suite of algorithms to train on top of the dynamics models, similar to RL<sup>2</sup>
- **Tested** on the real environment to verify transfer and **derived** lower bounds for the required data density

<b>Place Recognition in Unstructured Environments</b> <i>PhD Researcher at Oxford Robotics Institute</i>	May 2023 – Jul 2023 Oxford, UK
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- **Implemented** multiple point cloud transforms to test state-of-the-art place recognition networks
- **Utilized** large network backbones in PyTorch and applied them to in-house datasets for SLAM problems

## Work and Teaching

Research Mentor at <b>Lumiere Education</b>	Jun 2023 – Sep 2024
IT Assistant at <b>Wadham College</b>	Jan 2023 – Dec 2024
Executive Team member at the <b>Rhodes Trust Incubator</b>	Oct 2022 – Jul 2023

## Selected Publications and Conferences

### Leading or Co-First Author:

*A Clean Slate for Offline RL* **NeurIPS 2025 Main Track (Oral, top 0.38%)** (2025)  
*Web Agents at the Edge of Learnability Inside World Models* **Under Review** (2025)  
*Intent Factored Generation: Unleashing the Diversity in Your Language Model* **ICML 2025 Workshop on Exploration in AI Today** (2025)  
*Robust Learning via Adversarial World Models* **NeurIPS Workshops Open World Models and Adversarial ML** (2024)  
*Towards Reinforcement Learning Controllers for Soft Robots using Learned Environments* **IEEE Conference on Soft Robotics** (2024)

### Middle Author:

*Asynchronous Quadrature-phase Undersampling Technique for Wide-frequency Impedance Measurement* **IEEE Transactions on Instrumentation and Measurement** (2025)  
*SOReL and TOReL: Two Methods for Fully Offline Reinforcement Learning* **Arxiv** and **ICLR 2026 Under Review** (2025)  
*DARE: The Deep Adaptive Regulator for Control of Uncertain Continuous-Time Systems* **ICML Workshop on RL and Controls** (2024)

## Awards

<b>First Place in the G-Research Quant Challenge at Oxford</b>	2024
<b>Best Public Research Engagement Project with a Computer Vision inspired interactive game</b>	2023
<b>Rhodes Scholarship and EPSRC Funding Doctoral Training in AI and Robotics</b>	2022
<b>Most Technically Advanced Demo in the Social Robotics Symposium</b>	2019
<b>Regional Distinction in American Math Comp. and 6 National Olympiad wins including Physics and Chemistry</b>	2017 - 2018