# **Uljad Berdica**

## **Education**

University of Oxford Sep 2022 – Sep 2026

PhD with CDT-Autonomous Intelligent Machines and Systems, Rhodes Scholar 2022

Oxford, UK

New York University (NYU)

Aug 2018 – May 2022

Bachelor of Science in Electrical Engineering, Magna Cum Laude, University Honors

USA, UAE, PRC

#### **Research Work**

#### Al Research Associate for Reinforcement Learning and Optimization

Jun 2025 - Oct 02025

Research Scientist in the Optimization Team at JP Morgan Al Research

London, UK

- Inspect datasets of transactions and prices from various statistical perspectives
- Model trading problems to design and implement production-ready high-performance solutions
- Develop benchmarks and methods for bandit algorithms using natural language context and LLMs as stochastic processes

## Unified Offline Reinforcement Learning - JAX Library

Aug 2024 - Apr 2025

PhD Researcher at Foerster Lab for Al Research

Oxford, UK

- Implemented SOTA offline RL algorithms in a unified framework in JAX
- · Clean and consistent algorithmic implementation to track all the relevant tricks required for each method
- Evaluation of algorithms using a multi-armed bandit to estimate the online interaction budget required to find the best policy

# **Diverse Generation for Large Language Models**

Jul 2024 - June 2025

Researcher at Foerster Lab for Al Research and BBC Research and Development

Oxford, UK

- · Curated dataset from published user activity in large social networks and used to fine-tune LLMS
- Trained large models using three levels of tensor parallelism on multiple machines
- Implemented different clustering algorithms to evaluate the quality and the semantic entropy of the generations

# Towards Training Generalist Agents Through an Ensemble of World Models

Jan 2023 - Oct 2024

PhD Researcher at Foerster Lab for Al Research

Oxford, UK

- Trained 100s of dynamics models in parallel to use as levels to create a training curriculum
- Implemented a recurrent actor-critic network and a suite of algorithms to train on top of the dynamics models, similar to RL<sup>2</sup>
- · Tested on the real environment to verify transfer and derived lower bounds for the required data density

### **Place Recognition in Unstructured Environments**

May 2023 - Jul 2023

PhD Researcher at Oxford Robotics Institute

Oxford, UK

- Implemented multiple point cloud transforms to test state-of-the-art place recognition networks
- · Utilized large network backbones in PyTorch and applied them to in-house datasets for SLAM problems

## Work and Teaching

Research Mentor at Lumiere Education

IT Assistant at Wadham College

Executive Team member at the Rhodes Trust Incubator

Jun 2023 – Sep 2024

Jan 2023 – Dec 2024

Executive Team member at the Rhodes Trust Incubator

Oct 2022 – Jul 2023

# **Selected Publications and Conferences**

**Leading or Co-First Author:** 

A Clean Slate for Offline RL NeurIPS 2025 Main Track (Oral, top 0.38%) (2025)

Web Agents at the Edge of Learnability Inside World Models Under Review (2025)

Intent Factored Generation: Unleashing the Diversity in Your Language Model EXAIT @ ICML, ACL under review (2025)

Robust Learning via Adversarial World Models NeurIPS Workshops Open World Models and Adversarial ML (2024)

Towards Reinforcement Learning Controllers for Soft Robots using Learned Environments" IEEE Conference on Soft Robotics (2024)

## Middle Author:

Asynchronous Quadrature-phase Undersampling Technique for Wide-frequency Impedance Measurement IEEE Transactions on Instrumentation and Measurement (2025)

SOReL and TOReL: Two Methods for Fully Offline Reinforcement Learning Arxiv and ICLR 2026 Under Review (2025)

DARE: The Deep Adaptive Regulator for Control of Uncertain Continuous-Time Systems ICML Workshop on RL and Controls (2024)

### **Awards**

First Place in the G-Research Quant Challenge at Oxford	2024
Best Public Research Engagement Project with a Computer Vision inspired interactive game	2023
Rhodes Scholarship and EPSRC Funding for Doctoral Training in AI and Robotics	2022
Most Technically Advanced Demo in the Social Robotics Symposium	2019
Regional Distinction in American Math Comp. and 6 National Olympiad wins including Physics and Chemistry	2017 - 2018